

119 measures the force of gravity along an axis (shown by arrowed lines in FIGS. 1 and 2), and periodically sends measurement signals to processor 121. When display 103 is oriented as shown in FIG. 1, the axis of accelerometer 119 is nearly parallel to the direction of gravity. Therefore, accelerometer 119 measures nearly the full force of gravity when display 103 is in the upright orientation of FIG. 1. When display 103 is oriented as shown in FIG. 2, the axis of accelerometer 119 is nearly perpendicular to the direction of gravity. Therefore, accelerometer 119 measures very little, if any, of the force of gravity in the flat orientation of FIG. 2.

[0024] Processor 121 can receive the measurement signals from accelerometer 119 and determine the orientation of display 103 based on the measured force of gravity. If the measured force of gravity is below a predetermined threshold, processor 121 can determine that display 103 is oriented for a touch input mode. On the other hand, if the measured force of gravity is above the predetermined threshold, processor 121 can determine that display 103 is oriented for a keyboard/mouse input mode. The predetermined threshold may be customizable by the user. For example, a user may be able to select a threshold vertical angle (tilt) of display 103, which would correspond to a particular force measurement of accelerometer 119. In this case, for example, if a user selected a threshold angle of 60°, processor 121 can select a keyboard/mouse input mode when display 103 is oriented in the range of 90° (i.e., completely upright/vertical) to 60° (i.e., 60° between a plane of the ground and a plane of the display). Processor 121 can select a touch input mode when display 103 is oriented in the range of 60° to 0° (i.e., 0° between the plane of the ground and the plane of the display).

[0025] When processor 121 determines (based on the measured force of gravity) that angle of display 103 has crossed the predetermined threshold, i.e., the orientation of display 103 has changed from a touch input mode to a keyboard/mouse input mode, or vice versa, the processor can activate a transition process, such as the example transition process described below with respect to FIGS. 6 to 8.

[0026] Another example system for transitioning between a high-resolution input mode and a low-resolution input mode according to embodiments of the invention will now be described with reference to FIGS. 3 and 4. Similar to the example system shown in FIGS. 1 and 2, FIGS. 3 and 4 show a computer system 300 including a housing 301, display screen 303, an adjustable stand 305, and a keyboard 307. Adjustable stand 305 includes a lower base 309, an arm 311, an attachment post 313, a base hinge 315, and a post hinge 317. Unlike the previous example system, the system of FIGS. 3 and 4 includes an upper rotation sensor 319 at post hinge 317 and a lower rotation sensor 321 at base hinge 315. Upper rotation sensor 319 measures a rotation position of post hinge 317, and lower rotation sensor 321 measures a rotation position of base hinge 315. Rotation sensors 319 and 321 may be, for example, mechanical sensors, electromagnetic sensors, piezoelectric sensors, etc. Rotation sensors 319 and 321 can be coupled with a processor 323, which is located in housing 301.

[0027] FIG. 3 shows the computer system 300 oriented for a keyboard/mouse input mode. That is, similar to the previous example embodiment, when display 303 is oriented relatively upright, high, and further away from the user, a keyboard/mouse input mode is selected.

[0028] FIG. 4 shows computer system 300 oriented for a touch-based input mode. Similar to the previous example

embodiment, FIG. 4 shows display 303 oriented relatively flat, low, and closer to the user, in comparison to the orientation shown in FIG. 3, that is, housing 301 has been pulled toward the user and pushed down flat, such that display 303 is now oriented for a touch input mode.

[0029] The change in the orientation of display 303 can be detected by processor 323 based on angle measurements received from rotation sensors 319 and 321. Specifically, lower rotation sensor 319 measures the angle between arm 311 and attachment post 313, and periodically sends measurement signals to processor 323. Upper rotation sensor 321 measures the angle between lower base 309 and arm 311, and periodically sends measurement signals to processor 323. When display 303 is oriented upright as shown in FIG. 3, the angle between arm 311 and attachment post 313 is approximately 90°, and the angle between lower base 309 and arm 311 is also approximately 90°. When display 303 is oriented as shown in FIG. 2, the angle between arm 311 and attachment post 313 is approximately 270°, and the angle between lower base 309 and arm 311 is approximately 30°.

[0030] Processor 323 can receive the measurement signals from rotation sensors 319 and 321, and determine the orientation of display 303 relative to a plane of lower base 309 based on the measured angles. If the measured angles indicate that the orientation of display 303 is below a predetermined threshold (for example, if the angle between a plane of display 303 and the plane of lower base 309 is less than 60°), processor 323 can determine that display 303 is oriented for a touch input mode. On the other hand, if the measured angle is above the predetermined threshold (for example, if the angle between the plane of display 303 and the plane of lower base 309 is less than 60°), processor 323 can determine that display 303 is oriented for a keyboard/mouse input mode. Similar to the previous example embodiment, the predetermined threshold may be customizable by the user.

[0031] When processor 323 determines that the orientation of display 303 has crossed the predetermined threshold, i.e., the orientation of display 303 has changed from a touch input mode to a keyboard/mouse input mode, or vice versa, the processor can activate a transition process, such as the example transition process described below with respect to FIGS. 6 to 8.

[0032] FIG. 5 illustrates an example feature to help detect a change in display orientation between a high-resolution input mode and a low-resolution input mode according to embodiments of the invention. FIG. 5 shows a display screen 501 in a housing 503. Housing 503 includes touch sensor areas 505 that detect touch. Touch sensor areas 505 can, for example, be wrapped around to the back of housing 503 (not shown). When a user wishes to change the orientation of display screen 501, the user will typically grab housing 503 at touch sensor areas 505. When the user grabs touch sensor areas 505, the touch sensor areas send touch detection signals to a processor (not shown). The touch detection signals can be used in addition to other orientation sensor signals, such as described above, to help detect that the user has changed the orientation of display 501.

[0033] For example, as shown in FIG. 5, display 501 is in a relatively upright orientation, which might be a default orientation known by the processor. When the processor receives touch detection signals from sensor areas 505 followed by a change in orientation information received from other sensors, the processor may be better able to determine that the user has caused a change in the orientation of display